A Study of Desiccant-Based Cooling and Dehumidifying System in Hot-Humid Climate

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Abstract—The objective of this study is to investigate the feasibility of using desiccant cooling system as an alternative HVAC solution in buildings to achieve thermal comfort. This solution is more attractive when the solar energy is used to regenerate the desiccant wheel. An extensive experimental study has been performed in Tohoku University in Japan. A TRNSYS model of the desiccant cooling system combined with the heat wheel and heat source has been simulated and compared with the experimental data. The results of the simulation show that such system is feasible for cooling building in hot-humid climates.

Index Terms—Cooling, desiccant wheel, hot-humid climate.

I. INTRODUCTION

The building sector (commercial and residential) consume large amount of energy to support its operation and maintenance. Moreover, the large part of the energy demand by building is used to support indoor thermal comfort condition.

The provision of the building indoor thermal comfort conditions either through heating or cooling is done by the heat pumping system. These devices are called the mechanical vapor compression system [1]. Several researches are conducted to improve the system performance. However, the system still consumes a huge amount of energy. The main energy source of the mechanical vapor compression system is the electric energy from the grid line. In the Middle East, more than 70% of the building energy consumption is to support cooling [2]. In Europe, 10% of the building sector energy consumption is like wise to support cooling demand [3]. In Hong Kong, 45% of the commercial building energy consumption is also for cooling [4]. In Japan, 3% of the building sector energy consumption is for cooling application [5]. It is expected that in tropical countries which are hot and humid, energy demand for cooling and dehumidification is very high [6].

Alternative air-conditioning (AC) system which utilizes alternative materials, process, and energy resources can largely reduce building energy consumption [7, 8]. Among the alternative AC systems the desiccant cooling systems which can be operated through direct thermal energy, are important options for building cooling.

The desiccant air conditioning system utilizes the capability of desiccant materials in removing the air moisture content by sorption process. The sorption process (adsorption and absorption) is an interaction between the sorbent and sorbate molecule through intermolecular interaction [1]. Since desiccant materials have low concentration of water content, the air moisture content is attracted to the surface of the desiccant materials due to the moisture vapor pressure difference between the air and the desiccant surface. [1]. In order for the desiccant material to be used again, application of thermal energy is necessary to remove the moisture from the desiccant materials [1]. Fig. 1 shows the basic concept and diagram of the thermally activated desiccant cooling technologies.

II. SOLID DESICCANT COOLING PRINCIPLES AND CONCEPT

A. Concept and Operation

The solid desiccant cooling system is primarily based on the application of solid-based desiccant materials in controlling air moisture content. The sorption mechanism in the solid material is either through absorption or adsorption. Cooling by means of heat recovery, evaporative cooling or other means are applied to the system [1].

The solid desiccant material is the most widely used in desiccant cooling system. This is due to the simple handling of desiccant materials. The desiccant material is typically impregnated to the honeycomb designed wheels or of the cross-flow heat exchangers [1].

B. Development and Evolution

The most common solid desiccant cooling system is composed of two wheels types or called the Munter Cycle shown in Fig.1. This is the basic design of the solid desiccant cooling system. The application of the desiccant wheel as the air dehumidifier has factors to be considered. It has been shown that the performance of the desiccant-based cooling...
and dehumidification system relies much on the desiccant material [9]. Kodama et al. shows that there is an optimal speed by which high sorption rate exists in the rotation desiccant wheel [10]. Gao et al. shows that the thickness of the desiccant material affects the sorption capacity [11]. At higher desiccant material thickness in the channel, higher sorption rate is attained due to more time to reach the steady state.

III. EXPERIMENTAL FACILITIES

Fig. 2 shows the physical set-up of the experimental facility. The two chambers A and B are used to simulate the outdoor and indoor air conditioning [12]. Chamber A has temperature range from -10°C to 40°C with accuracy of 2%. For chamber B, the operating temperature range is from 10°C to 40°C with accuracy of within 1%. For both chambers the humidity could be varied depending on the needed conditions.

The main components of the desiccant based system consist of desiccant dehumidifier wheel, heat recovery wheel and heater. The performance of the whole system is dependent on the performance of its components. This task has been already conducted in the laboratory in Tohoku University [13] and the main results are presented below. The parameters considered for the evaluation were the rate of volumetric flow; the regeneration temperature and the wheel rotational speed (see Table I).

![Fig. 2. Experimental facilities.](image)

| TABLE I: PARAMETERS USED TO EVALUATE THE PERFORMANCE OF THE DESICCANT COOLING SYSTEM |
|-----------------------------------|------------------|------------------|------------------|
| Rate of volumetric flow [m³/hr] | 100              | 200              |
| Regeneration temperature [°C]    | 60               | 70               | 80               |
| Wheel rotational speed [RPH]     | 5                | 10               | 20               | 25               | 30               | 35               | 40               | 50               | 60               |

IV. MODELING AND SIMULATION

The typical desiccant cooling air system as shown in Fig. 1 is an open heat driven cycle which comprises a desiccant wheel in tandem with a thermal wheel. A regeneration coil located in the return air stream drives the whole cycle.

The psychrometric chart shown in Fig. 3 illustrates the cooling/dehumidification process. During the summertime hot moist air at for example 35 °C and 21 g/kg moisture content is drawn through the desiccant wheel so that it comes at say 45 °C and 18 g/kg moisture content. The supply air stream then passes through the thermal wheel where it is sensibly cooled to say 30 °C.

On the return air side, air from the room space at for example, 31 °C and 24 g/kg moisture content enters the thermal wheel. As the return air stream passes through the thermal wheel, it is sensibly heated. The air is then heated up to approximately 60 °C in order to regenerate the desiccant coil. It should be noted that in order to reduce system operation costs approximately 20% of the return air flow by-passes the regenerating oil and the desiccant wheel [14].

![Fig. 3. Psychrometric chart showing a typical desiccant cooling process.](image)

![Fig. 4. The schematic diagram of the desiccant wheel (DW) and heat wheel (HW).](image)
The amount of moisture removal capacity or sorption rate is the same at the regeneration side which is the moisture removal regeneration (MRR) expressed as

\[ MRR = m_{RA}(AH_{EA} - AH_{RA}) \tag{2} \]

To evaluate the characteristic and performance of the experiment, the moisture mass balance (MBB) determined the quality of gathered data and thus the MBB is a checking factor and expressed as

\[ MBB = \frac{MRC}{MRR} \tag{3} \]

where \( m_{OA} \) and \( m_{EA} \) are the mass flow rates from the outside and regeneration side of the DW in kg/s, respectively. \( AH_{OA}, AH_{PA}, AH_{EA}, \) and \( AH_{RA} \) are the absolute humidities of the outside air, processed air, exit air and regeneration air, respectively, g/kg moisture content.

For acceptable accuracy of gathered data, the ratio of MBB should be within 0.5 to 1.5.

**B. Heat Wheel**

The heat wheel is coated with silicone-acrylic compound. The physical appearance and dimension of the heat wheel is the same as the desiccant wheel. The main purpose of the heat wheel is for sensible heat recovery only (inlet and outlet), °C and kg.

**Separate wheel is for sensible heat recovery only**

\[ \text{Eff}_{\text{Average}} = \frac{m_{CS}(T_{C(I)} - T_{C(O)}) + m_{HS}(T_{H(I)} - T_{H(O)})}{2m_{\text{Minimum}}(T_{H(I)} - T_{C(I)})} \tag{4} \]

\( m_{CS} \) and \( m_{HS} \) are the mass flow rates (hot and cold sides), kg/s. \( T_{C(I)} \) and \( T_{C(O)} \) are the temperature of air in the cold side (inlet and outlet), °C. \( T_{H(I)} \) and \( T_{H(O)} \) are temperature of air in the hot side inlet and outlet, °C and \( m_{\text{Minimum}} \) is the minimum flow rate of either hot or cold side, kg/s.

**V. RESULTS AND DISCUSSION**

Fig. 5 shows the schematic diagram of the basic desiccant model which was under experimental investigation. This basic model is used for comparison with the experimental data obtained previously. Standard component such as DW, HW and heater were used to simulate the thermal behavior of the whole system under hot-humid climate using TRNSYS which is an abbreviation of Transient Simulation.

TRNSYS is a simulation environment and an open modular structure for the transient simulation of system used to validate new energy concepts. A TRNSYS project is typically set up by connecting components graphically in the simulation studio [16]. The two effectiveness value of the DW proposed by Banks which is discussed in TRNSYS manual have been used in the simulation.

The basic model of the DW combined with HW and heater for the DW regeneration shown in Fig. 4 has been validated against the experimental published data [13]. Table 2 shows the comparison between the experimental data and the simulated ones.

The air conditions for the outdoor air (point 1) are set at value of 30°C and 60% RH. The volumetric flow rate is 120 m³/h, the return air (point 4) is set at value of 26°C and 55% RH and flow rate of 120 m³/h. The result of the simulation shows that the DBT and RH are within the accepted range compared with the experimental ones. The differences are mainly due to the initial value of some intrinsic parameters of the model such as the DW and HW effectivenesses, which must be thoroughly investigated and adjusted in the future.

The basic model of the desiccant cooling system is limited in term of input data of the DBT. Indeed, for high DBT, TRNSYS does not have the capability to converge towards the solution. Therefore, a pre-cooling system using indirect evaporative cooler IEC will solve the problem. The Desiccant cooling system with IEC is shown in Fig. 6. It can be seen that the Rh of the supply air (state 4) decreases by 24%, while the DBT decreases by 9% compared with the outdoor conditions. By adding direct evaporative cooler DEC as shown by Fig. 7 the DBT drops to 29°C and Rh rises to 59% which are considered as appropriate indoor condition for thermal comfort.

**TABLE II: EXPERIMENTAL AND SIMULATION RESULTS**

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Fig. 5. Simulation result of the basic desiccant cooling system.

Fig. 6. Schematic diagram of the standard desiccant cooling system with pre-cooling.
VI. CONCLUSION

The desiccant cooling system presented in this paper which combines the desiccant wheel with heat wheel can be a suitable solution for hot-humid climate. The basic model by means of TRNSYS has been validated against the experimental data obtained from Tohoku University in Japan.

Combining the basic desiccant model with IEC and DEC allows reducing significantly the DBT to 29°C and keeping Rh within the accepted value 59% considering hot-humid outside climate at 36°C and 70%.

The performance of the desiccant cooling system will be studied more for further improvements. One of these improvements is to combine with the desiccant cooling system a solar air heating system for the DW regeneration.

ACKNOWLEDGMENT

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REFERENCES

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