Swimming Pattern Generator Based on Diving Beetles for Legged Underwater Robots

Hee-Joong Kim and Jihong Lee

ANFIS PD+I Based Hybrid Force/ Position Control of an Industrial Robot Manipulator

Himanshu Chaudhary, Vikas Panwar, N. Sukavanam, and Rajendra Prasad

Evaluating the Cutting Mechanics of Woodworking Hand-Saw Teeth

Andrew Naylor

Connection between Parameters of Timing Diagram of Automatic Machine and Equations Movements of Mechanisms

A. Jomartov, S. Joldasbekov, and Y. Temirbekov

Conceptual Design of 3 Independent Motor Actuation Transmission Systems for Low-Cost Anthropomorphic Prosthetic Hand

Anggriyawan Putranto, Ilham Priadythama, Susy Susmartini, and Pringgo W. Laksono

Importance of Locomotion and Its Dominance over Other Factors

Shruti Mundra and Shiv Bhagwan Agarwal

A Real-Time Fall Detection System in Elderly Care Using Mobile Robot and Kinect Sensor

Zaid A. Mundher and Jiaofei Zhong

A Stochastic Programming Approach to Supply Chain Disruptions Planning and Management

S. M. Ali and K. Nakade

Some Observations on Resource Allocation in Assembly-Like Queueing Networks via Simulation Approach

Yu Song and Masayoshi Hasama

Complex Production Structures in Assembly Processes

W. Grzechca

Availability Analysis with Opportunistic Maintenance of a Two Component Deteriorating System

Joel P. Varghese and Girish Kumar

Design of Confectionery Slicer for SME’s Product Quality Improvement

Sri Indrawati, Tio Sampurno, Yogi Thanjaya, and Rahmadani R. Octaviani

Mechanical Properties of Rice Husks Fiber Reinforced Polyester Composites

I Wayan Surata, I Gusti Agung Kade Suriadi, and Krissanti Arnis

Knowledge Integration in Collaborative New Product Development of Large Commercial Aircraft of China
Li Zhengfeng

Fuzzy Logic Control Application for the Prototype of Gun-Turret System (ARSU 57 mm) Using Matlab…174

Munadi, Joga Dharma Setiawan, and Muhammad Fairuz Luthfu